

Perceptual Fusion Tendency of Speech Sound

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Abstract

■ To discriminate and to recognize sound sources in a noisy, reverberant environment, listeners need to perceptually integrate the direct wave with the reflections of each sound source. It has been confirmed that perceptual fusion between direct and reflected waves of a speech sound helps listeners recognize this speech sound in a simulated reverberant environment with disrupting sound sources. When the delay between a direct sound wave and its reflected wave is sufficiently short, the two waves are perceptually fused into a single sound image as coming from the source location. Interestingly, compared with nonspeech sounds such as clicks and noise bursts, speech sounds have a much larger perceptual fusion tendency. This study investigated why the fusion tendency for speech sounds is so large. Here we show that

when the temporal amplitude fluctuation of speech was artificially time reversed, a large perceptual fusion tendency of speech sounds disappeared, regardless of whether the speech acoustic carrier was in normal or reversed temporal order. Moreover, perceptual fusion of normal-order speech, but not that of time-reversed speech, was accompanied by increased coactivation of the attention-control-related, spatial-processing-related, and speech-processing-related cortical areas. Thus, speech-like acoustic carriers modulated by speech amplitude fluctuation selectively activate a cortical network for top-down modulations of speech processing, leading to an enhancement of perceptual fusion of speech sounds. This mechanism represents a perceptual-grouping strategy for unmasking speech under adverse conditions. ■

INTRODUCTION

Investigation of how various sound sources (including speech sounds) are discriminated and a target source is correctly recognized in a noisy, reverberant environment is critical for reaching the understanding of why the human brain is able to extract target information under conditions with sensory-input “flooding.” It has been confirmed that to distinguish signals from various speech sources and to correctly recognize the target speech source in a simulated reverberant environment, listeners need to not only perceptually integrate the direct wave with the reflections of the target speech source (Huang, Huang, Chen, Wu, & Li, 2009; Huang, Huang, et al., 2008) but also perceptually integrate the direct wave with the reflections of the masking speech source (Rakerd, Aaronson, & Hartmann, 2006; Brungart, Simpson, & Freyman, 2005).

When the delay between a leading sound (such as the direct wave from a sound source) and a correlated lagging sound (such as a reflection of the direct wave) is sufficiently short, attributes of the lagging sound are perceptually captured by the leading sound (Li, Qi, He, Alain, & Schneider, 2005), causing a single fused sound image from a location near the leading source (the precedence effect, see Litovsky, Colburn, Yost, & Guzman, 1999; Freyman, Clifton, & Litovsky, 1991; Zurek, 1980; Wallach, Newman, &

Rosenzweig, 1949). This perceptual fusion is able to produce *perceived* spatial separation between uncorrelated sound sources, and the *perceived* spatial separation plays a role in reducing masking for speech recognition (Huang, Huang, et al., 2008, 2009; Rakerd et al., 2006; Wu et al., 2005; Li, Daneman, Qi, & Schneider, 2004; Freyman, Helfer, McCall, & Clifton, 1999). For example, when both the target and the masker are presented by a loudspeaker to the listener’s left and by another loudspeaker to the listener’s right, the perceived location of the target and that of the masker can be manipulated by changing the interloudspeaker interval for the target and that for the masker (Li et al., 2004). More specifically, for both the target and the masker, when the sound onset of the right loudspeaker leads that of the left loudspeaker by a short time (e.g., 3 msec), both a single target image and a single masker image are perceived by the human listener as coming from the right loudspeaker. However, if the onset delay between the two loudspeakers is reversed only for the masker, the target is still perceived as coming from the right loudspeaker, but the masker is perceived as coming from the left loudspeaker. The perceived colocation and the perceived separation are based on perceptual integration of correlated sound waves delivered from each of the two loudspeakers. It has been confirmed that perceived target-masker spatial separation facilitates the listener’s selective attention to target signals and significantly improves recognition of target signals, although neither the masker

energy at each ear nor the stimulus-image compactness/diffusiveness is substantially changed (e.g., Li et al., 2004).

The minimum delay allowing a listener to perceive the lagging sound as a discrete echo (when the perceptual fusion is just broken) is called the echo threshold (Litovsky et al., 1999; Freyman et al., 1991), which indicates the perceptual fusion tendency (i.e., a large echo threshold suggests a large perceptual fusion tendency). Interestingly, speech sounds, which are the most important acoustic stimuli for human communication and contain distinct patterns of periodicities and transients, have much larger echo thresholds than other types of sounds such as clicks and noise bursts (Rakerd, Hartmann, & Hsu, 2000; Litovsky et al., 1999; Lochner & Burger, 1958; Cherry & Taylor, 1954; Wallach et al., 1949).

This study investigated why the tendency of the perceptual fusion of speech sounds is so large. Because the temporal properties of speech sounds are critical for achieving communication (Rosen, 1992), the focus of this study was particularly on the role played by the overall temporal amplitude fluctuation (TAF) of speech in maintaining the perceptual fusion tendency and in eliciting perceptual-fusion-related cortical activations.

The TAF of Chinese speech was extracted using the Hilbert transform as previously used by other investigators (Zeng et al., 2005; Smith, Delgutte, & Oxenham, 2002). When the speech TAF is artificially removed from speech, the remaining acoustic component is called the speech acoustic carrier (AC), which still contains some speech acoustic features including harmonic structures, frequency modulation, and periodic occurrences of noise-like consonants. When the TAF and the AC are artificially separated, they can be time reversed either independently or at the same time. Any of the temporal reversals does not change the long-term spectrum, the fundamental frequency, and other spectrotemporal characters, including the overall spectral modulation density, the temporal modulation frequency, and the modulation amplitude. The modified speech sound is still “speech-like” but has reduced or no semantic content.

EXPERIMENT 1

Method

Participants

Eighteen university students (12 women and 6 men, 19–28 years old, mean age = 23 years) participated in this experiment. In this and the following three experiments (Experiments 2–

previous investigators (Zeng et al., 2005; Smith et al., 2002): spectrum-matched steady-state noise, normal-order speech, and time-reversed speech. To obtain the normal-order speech AC, the normal-order speech was multiplied by the ratio of the TAF of the spectrum-matched steady-state noise to the TAF of the normal-order speech. Thus, the normal-order speech AC had the fine structures of the normal-order speech and the TAF of the spectrum-matched steady-state noise (Drullman, Festen, & Plomp, 1994). Similarly, to obtain the time-reversed speech AC, the time-reversed speech was multiplied by the ratio of the TAF of the spectrum-matched noise to the TAF of the time-reversed speech.

Procedure

Participants pressed a button of the response box to initiate a test session. For each of the three sound types, sounds delivered from the two loudspeakers were identical in a trial. The right loudspeaker always led the left loudspeaker. Participants were instructed to indicate whether they perceived a discrete sound from the location around the left loudspeaker by pressing the left button of the response box or nothing from the location around the left loudspeaker by pressing the right button. The time lag between the two loudspeakers (called the lead/lag delay) was decreased following the participant's three successive responses, indicating that a sound around the left loudspeaker location was perceived, and increased following one response, indicating that no sound was perceived from the left loudspeaker, using a three-down-one-up procedure (Levitt, 1971). No feedback was given to participants. The testing order for the three types of sounds was counterbalanced among the 18 participants according to the Latin square design.

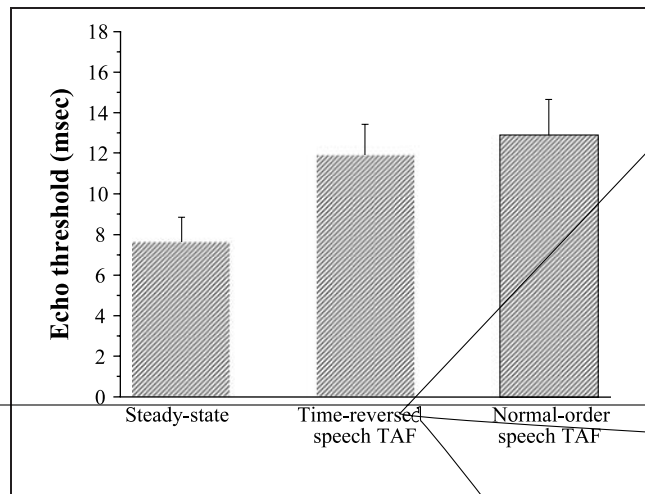
Each session was started with the lead/lag delay of 72 msec. The initial step size of changing the lead/lag delay was 16 msec, and the step size was altered by a factor of .5 with each reversal of direction until the minimum size of 1 msec was reached. A test session was terminated following 10 reversals in direction, and the echo threshold for that session was defined as the averaged lead/lag delay for the last six reversals. For each participant under each condition, there were four test sessions. The averaged echo threshold of the four sessions was used as the echo threshold for the participant under the condition. During testing, the participant was instructed to keep his or her head still and face the midline in the frontal area, but the head was not physically fixed.

In this and in the following psychophysical experiments (Experiments 1–3), sounds from the loudspeakers were calibrated using a B&K sound level meter (Type 2230) whose microphone was placed at the position of the head when the listener was absent, using a “slow”/“RMS” meter response. All sounds were presented at a level such that each loudspeaker, playing alone, would produce a comfortable sound pressure of 56 dBA SPL.

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In Experiment 1, both TAF information of normal-order speech and TAF information of time-reversed speech were removed by replacement of these speech TAFs with the TAF of spectrum-matched steady-state noise. The echo threshold of the spectrum-matched steady-state noise was significantly lower than both the echo threshold of the normal-order speech AC ($p = .011$, two-tailed paired samples t

speech. To obtain the spectrum-matched noise modulated by the TAF of normal-order speech (the modulated noise had the same AC as the spectrum-matched steady-state noise and the TAF of the normal-order speech), the spectrum-matched steady-state noise was multiplied by the ratio of the TAF of normal-order speech to the TAF of the spectrum-matched steady-state noise (Drullman et al., 1994). Similarly, to obtain the spectrum-matched noise modulated by the TAF of time-reversed speech, the spectrum-matched steady-state noise was multiplied by the ratio of the TAF of time-reversed speech to the TAF of the steady-state noise.



Procedure

The procedure was the same as used in Experiment 1. The testing order for these three types of sounds was counter-balanced among the 18 participants according to the Latin square design.

Results

In Experiment 2, both the TAF of normal-order speech and the TAF of time-reversed speech were extracted, and each of the two types of TAFs was used to modulate spectrum-matched steady-state noise. The echo threshold of spectrum-matched steady-state noise significantly increased after the noise was amplitude modulated by either the TAF of normal-order speech ($p < .001$, two-tailed paired samples t test with the significant level of $.05/3 = .0167$) or the TAF of time-reversed speech ($p = .001$), and the two types of amplitude-modulated noises did not differ significantly ($p > .05$) (Figure 2).

EXPERIMENT 3

Method

Participants

Twenty university students (8 women and 12 men, 19–25 years old, mean age = 22 years) participated in this experiment.

Apparatus

The apparatus was the same as used in Experiment 1.

Stimuli

Four types of Chinese speech or speech-like sounds were used in this experiment, which had different TAF and AC combinations: (a) normal-order TAF and normal-order AC, (b) time-reversed TAF and time-reversed AC, (c) normal-order TAF and time-reversed AC, and (d) time-reversed

TAF and normal-order AC. To obtain speech with the TAF of normal-order speech and the AC of time-reversed speech, the time-reversed speech was multiplied by the ratio of the TAF of normal-order speech to the TAF of time-reversed speech (Drullman et al., 1994). Similarly, to obtain speech with the TAF of time-reversed speech and the AC of normal-order speech, the normal-order speech was multiplied by the ratio of the TAF of time-reversed speech to the TAF of normal-order speech.

Procedure

The procedure was the same as used in Experiment 1. The testing order for the four types of sounds was counter-balanced among the 20 participants according to the Latin square design.

Results

Experiment 3 investigated whether the TAF of normal-order speech and the TAF of time-reversed speech are different in affecting the perceptual fusion tendency when the AC is of speech or speech-like. Echo-threshold comparisons were made across the following four types of Chinese speech or speech-like sounds with different TAF and AC combinations: (a) normal-order TAF and normal-order AC, (b) time-reversed TAF and time-reversed AC, (c) normal-order TAF and time-reversed AC, and (d) time-reversed TAF and normal-order AC. As shown in Figure 3, unlike the results of Experiment 2, speech sounds with the normal-order TAF had markedly larger echo thresholds than those with the time-reversed TAF.

An ANOVA confirms that the interaction between the temporal order of TAF and the temporal order of AC was not significant ($p > .05$), the main effect of temporal order of AC was not significant ($p > .05$), but the main effect of temporal order of TAF was significant, $F(1, 19) = 51.875$, $p < .001$.

EXPERIMENT 4

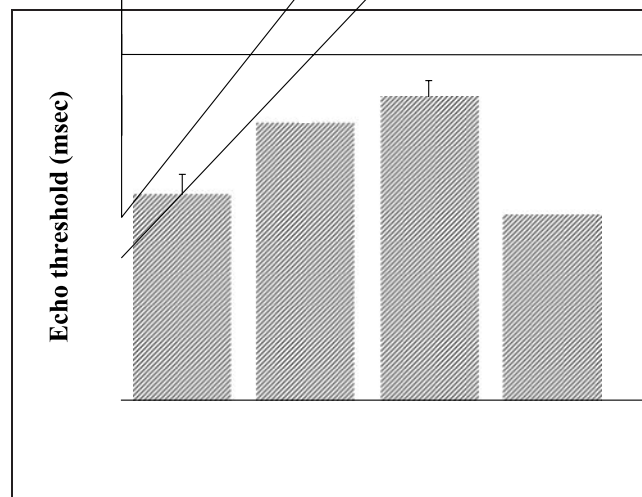
Method

Participants

Eight university students (two women and six men, 19–27 years old, mean age = 24 years) participated in this experiment.

Stimuli and Apparatus

A Knowles Electronic Manikin for Acoustic Research (KEMAR) was located at the center of the anechoic chamber that is described for Experiment 1. Two types of sounds were used in this experiment: normal-order speech (which were created and reproduced as in Experiment 1) and time-reversed speech, and they were the same as used in Experiment 3. Similar to Experiment 3, speech analog signals were delivered to two loudspeakers (Dynaudio Acoustics, BM6A) in the frontal azimuthal plane at the left and right 45° positions with respect to the median plane. For a recording trial, the two loudspeakers presented identical speech (either normal order or time reversed), with the left loudspeaker lagging behind the right loudspeaker by either 2 or 40 msec.



The loudspeaker height was 140 cm, which was at the ear level of KEMAR, and the distance between the loudspeaker and the center of the KEMAR was 200 cm. Sound waves were recorded using the KEMAR, which was equipped with the ear simulators (RA0045, G.R.A.S, Sound and Vibration, Holte, Denmark), a programmable front-end (BEQ II.0, Head-acoustic, Herzogenrath, Germany), and a sound-progressed software (ArtemiS 6.0, Head-acoustic). These recorded sound waves were presented to participants at the level of 77 dB SPL through two air-conduction headphones during fMRI data acquisition. A new speech sentence was used for each fMRI scanning trial.

Experimental Design

As indicated by the results of Experiment 3, the mean difference in echo threshold between normal-order speech and time-reversed speech was about 5 msec, and there were large between-participant fluctuations in echo threshold. For each of the two types of speech sounds used in Experiment 4 (the fMRI experiment), to ensure that (a) the shorter lead/lag delay (that was below the echo threshold) was the same across participants and the longer lead/lag delay (that was above the echo threshold) was also the same across participants, (b) the shorter lead/lag delay was short enough to induce perceptual fusion with a high degree of image compactness, and (c) the longer lead/lag delay was long enough to cause two discretely separated sound images, the shorter and longer lead/lag delays were set at 2 and 40 msec, respectively. Thus, there were four stimulus conditions (two sound types: normal-order speech and time-reversed speech; two lead/lag delays: 2 and 40 msec). For each condition, 60 scans were conducted, including 40 scans with speech stimuli and 20 scans with silence as the baseline. Both speech stimuli and silence presentations were delivered to each participant with a random manner. Thus, there were totally 240 scans for each participant. The order of the four conditions was counter-balanced across the eight participants.

fMRI Data Acquisition

Echo-planar brain images were acquired using a 3-T scanner (Siemens) with a standard single-channel head coil. Participants were instructed to close their eyes during scanning. A T2*-weighted gradient-echo EPI sequence was used. Each image set constituted 30 slices (slice thickness = 4 mm) to cover the whole brain. The following acquisition parameters were used: repetition time = 9 sec, echo time = 30 msec, flip angle = 90°, and voxel size = 3.75 × 3.75 × 5 mm³. Data acquisition was conducted in the last 1.8 sec of the repetition time, with a stimulus presented 6.7 sec before each scan (sparse temporal sampling, see Hall et al., 1999). Participants were instructed to press a button using their right thumb in response to the end of each scanning noise. For each participant, the individual high-resolution three-dimensional T1-weighted MR image was also collected after

functional image acquisition for coregistration and normalization of functional images.

fMRI Data Analyses

Under each stimulus condition, the first image in response to speech stimuli and both the first and the last images for the silence baseline were omitted from analyses. The remaining 228 scans for each participant were preprocessed using SPM2 software (<http://www.fil.ion.ucl.ac.uk>). The preprocessing of the functional images included realignment (rigid-body transformation), slice timing for adjusting head movements and slice acquisition delays, and coregistration with the anatomical data. The images were then normalized to the Montreal Neurological Institute space using nonlinear transformations and smoothed with a Gaussian kernel of 6-mm full width at half maximum. Statistical analyses at the first level implemented the general linear model that specified four variables encompassing the four stimulus conditions. Linear contrasts between stimulus conditions and baseline conditions (normal-order/2-msec delay vs. baseline, normal-order/40-msec delay vs. baseline, time-reversed/2-msec delay vs. baseline, and time-reversed/40-msec delay vs. baseline) were calculated to generate a contrast-parameter-estimate map for each participant. The contrast-parameter-estimate maps were then high-pass filtered at 256 sec to deal with the low-frequency artifacts. Then, at the second level, the high-pass filtered contrast images of the first level were submitted to a random-effect group analysis using one-way ANOVA. Activations were reported only if it exceeded a voxel-level significance threshold of $p < .05$ (uncorrected for multiple comparison) and extent threshold = 185 (Leff et al., 2008). To use an automated labeling system (Lancaster et al., 2000), the spatial coordinates of activation maxima were transformed from the Montreal Neurological Institute space into Talairach space (Brett, Johnsrude, & Owen, 2002).

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The results of the psychophysical experiments confirm that perceptual fusion of correlated leading and lagging sounds depends on the lead/lag delay. In Experiment 4, we used the fMRI method to investigate whether the cortical activations associated with perceptual fusion (when the lead/lag delay is sufficiently shorter than the echo threshold) are different from those associated with perceptual separation (when the lead/lag delay is sufficiently longer than the echo threshold), although the sounds presented from the leading and lagging sources are always identical. Moreover, because the results of Experiment 3 suggest that perceptual fusion of speech-like sounds also depends on whether the TAF is in normal or time-reversed order, Experiment 4 particularly investigated whether the cortical activations associated with perceptual fusion of normal-order speech are different from those associated with perceptual fusion of time-reversed speech.

Either normal-order speech or time-reversed speech was presented to the listeners at the two ears with headphones. Because the speech stimuli contained signals that were modified by the head-related transfer functions, when the stimulus at the right ear led that at the left ear by 2 msec (this lead/lag delay was far below the echo threshold), listeners experienced only one sound image as coming from the right semifield. Also, when the stimulus at the right ear led that at the left ear by 40 msec (this lead/lag delay was far above the echo threshold), listeners experienced two spatially separated sound images, one as coming from the right semifield and the other as coming from the left semifield.

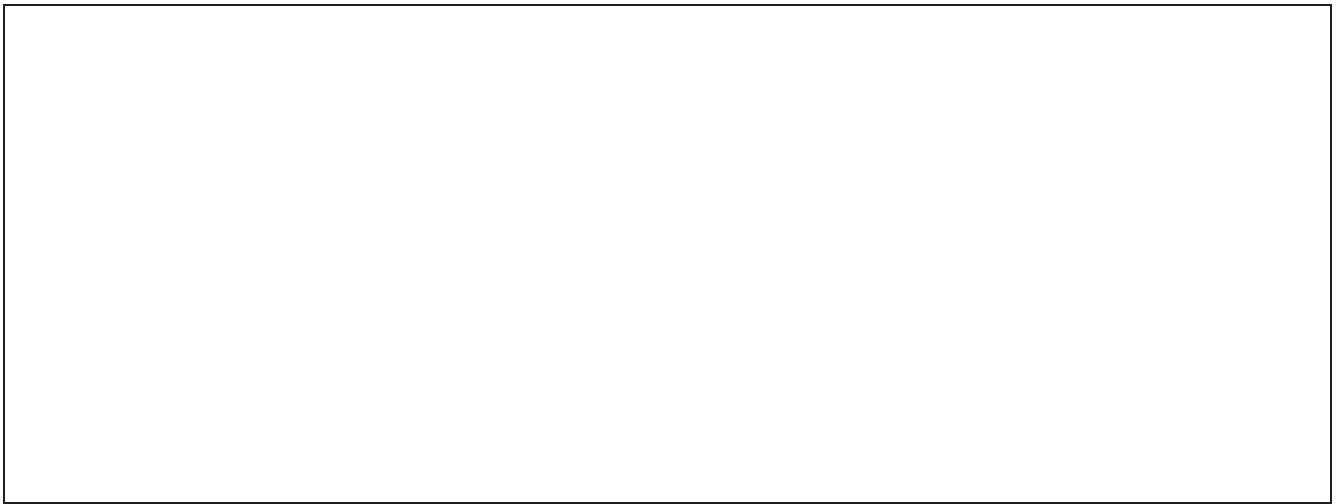
Compared with normal-order speech without perceptual fusion (when the lead/lag delay was 40 msec), perceptually fused normal-order speech (when the lead/lag delay was 2 msec) was associated with increased BOLD contrast activations in both the right ACC (Brodmann area [BA] 32) (top panels in Figure 4) and the left middle temporal gyrus (BA 21) (bottom panels in Figure 4). However, compared with time-reversed speech without perceptual fusion (when the lead/lag delay was 40 msec), perceptually fused time-reversed speech (when the lead/lag delay was 2 msec) was associated with increased BOLD contrast activations only in the left superior frontal gyrus (BA 10) (Figure 5).

Moreover, although both normal-order speech and time-reversed speech were perceived as a single fused image at the lead/lag delay of 2 msec, perceptually fused normal-order speech, compared with perceptually fused time-reversed speech, was associated with more BOLD activations in the right ACC (BA 32) (top panels in Figure 6), the right inferior parietal lobule (IPL, BA 40) (middle panels in Figure 6), and the left anterior part of the superior temporal gyrus (STG, BA 38) (bottom panels in Figure 6). However, these patterns of cortical activation did not occur for perceptual separation of normal-order speech against perceptual separation of time-reversed speech (Figure 7).

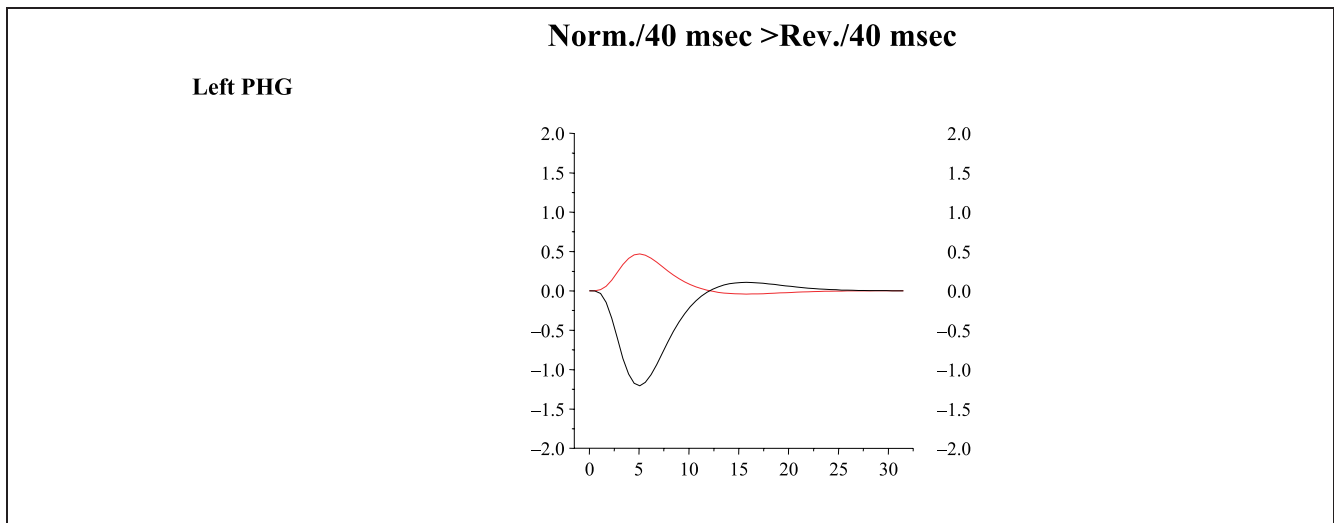
CALCULATING THE SPEED OF AMPLITUDE INCREASE AND THE SPEED OF AMPLITUDE DECREASE

In all, 432 sentences were used for the statistics. For each sentence, the TAF of the original wideband speech signal (16 bits at the sampling rate of 22,050 Hz) was obtained using the Hilbert transform. To ensure that the amplitude slope was sufficiently steep, the TAF was low-pass filtered at the cutoff frequency of 500 Hz, with the filter slope of approximately -40 dB/oct, and then down sampled to the sampling rate of 1000 Hz. Finally, the down-sampled TAF was low-pass filtered at the cutoff frequency of 50 Hz for calculating amplitude rises and falls.

The maximum amplitude of each envelope with the sampling rate of 1000 Hz was normalized to 1, and differences in amplitude between adjacent sampling points were obtained as either envelope rises (positive values) or envelope falls (negative values). To eliminate both silent and flat components, the amplitude differences were removed







from statistics if their absolute values were less than 0.0014. The results of the statistics show that the ratio of the mean positive rates to the mean negative rates was 1.252, which indicates that the amplitude rise was generally 25.2% faster than the fall.

DISCUSSION

In the present study, when the overall TAF of Chinese speech was extracted using the Hilbert transform (Zeng et al., 2005; Smith et al., 2002), the TAF and the AC could be artificially separated and manipulated independently. Although temporally reversing either the TAF or the AC does not change the long-term spectrum, the fundamental frequency, and other spectrotemporal features (including the overall spectral modulation density, temporal modulation frequency, and modulation amplitude), the speed of amplitude increase (the onset rate) for the TAF of normal-order Chinese speech is generally 25.2% faster than that for the TAF of time-reversed Chinese speech.

The results of Experiment 1 show that the echo threshold of the spectrum-matched steady-state noise, which did not contain any spectrotemporal modulations, was significantly lower than both the echo threshold of the normal-order speech AC and the echo threshold of the time-reversed speech AC, indicating that certain structural characters of speech AC, including harmonic structures, frequency modulation, and/or periodic occurrences of noise-like consonants, are able to enhance the tendency of the perceptual fusion. Because there was no significant difference between the two types of speech ACs, the temporal order of speech AC does not affect the enhancing effect.

The results of Experiment 2 show that when the AC was noise, amplitude modulation of the noise AC with either the TAF of normal-order speech or the TAF of time-

reversed speech equally enhanced the perceptual fusion tendency, indicating a general amplitude-modulation effect (Schubert & Wernick, 1969). However, on the basis of the Rakerd and Hartmann (1986) study using tones with various onset durations and other parameters, when the tone-onset duration is not longer than 100 msec, shortening the tone-onset duration (i.e., increasing the onset rate) can monotonically facilitate the precedence effect. In future studies, it is worth investigating whether artificially manipulating the general contrast between the onset rate and the offset rate of the TAF in a larger range can significantly affect the echo threshold of the noise that is amplitude modulated by the TAF.

The results of Experiment 3 show that speech sounds with the normal-order TAF had markedly larger echo thresholds than those with the time-reversed TAF. Thus, when the AC is of speech or speech-like, regardless of its temporal order, the TAF of normal-order speech plays a special role in maintaining the high tendency of speech fusion.

In summary, the results of these three psychophysical experiments indicate that the markedly high perceptual fusion tendency of speech sounds is caused by the amalgamation of at least three effects: (a) the temporally bidirectional effect of speech (or speech-like) AC (Experiment 1), (b) the temporally bidirectional effect of amplitude modulation (Experiment 2), and (c) the specific effect of amplitude modulation induced by the TAF of normal-order speech only when the AC is of speech (or speech-like) (Experiment 3).

The results of Experiment 3 indicate that relative to time-reversed speech, normal-order speech has a larger perceptual fusion tendency. The main objective of Experiment 4 was to examine whether the BOLD activations associated with perceptual fusion of normal-order speech are different

from those associated with perceptual fusion of time-reversed speech. The results of the fMRI experiment (Experiment 4) of this study for the first time show that compared with normal-order speech without perceptual fusion (when the lead/lag delay was 40 msec), perceptually fused normal-order speech (when the lead/lag delay was 2 msec) was associated with increased BOLD contrast activations in both the right ACC, which is involved in top-down attentional modulation of auditory processing (Crottaz-Herbette & Menon, 2006), and the left middle temporal gyrus, which is involved in both phonemic perception (Liebenthal, Binder, Spitzer, Possing, & Medler, 2005) and semantic processing (Friederici, 2002). However, compared with time-reversed speech without perceptual fusion, perceptually fused time-reversed speech was associated with increased BOLD contrast activations only in the left superior frontal gyrus.

Compared with perceptually fused time-reversed speech, perceptually fused normal-order speech was associated with more BOLD activations in the attention-control-related right ACC (BA 32), the right inferior parietal lobule (BA 40), which is a cortical area in the “where” pathway processing auditory spatial information (Wang, Wu, & Li, 2008; Arnott, Binns, Grady, & Alain, 2004; Alain, Arnot, Hevenor, Graham, & Grady, 2001; Weeks et al., 1999), and the left anterior part of the superior temporal gyrus (BA 38), which is involved in processing speech signals for comprehension (Hickok & Poeppel, 2007; Binder et al., 1997, 2000; Scott, Blank, Rosen, & Wise, 2000). These patterns of cortical activations did not occur for perceptual separation of normal-order speech against perceptual separation of time-reversed speech. These results suggest that when two correlated normal-order speech sounds become perceptually fused, both the cortical processing of speech-spatial information and that of speech-content information are enhanced. Moreover, these cortical processing enhancements are accompanied with a facilitation of cortical top-down attentional modulations of auditory processing. However, it should be noted that because of both the limitation in trial numbers and the long time of a trial cycle (9000 msec) in the fMRI experiment, the threshold-tracking procedure used in the psychophysical experiments was not applicable in the fMRI experiment. Thus, the temporally analytical level of the fMRI experiment did not match that of the

one of the loudspeakers. When the absolute value of intermasker interval was 32 msec or shorter, there was consistent evidence of release from speech masking for target speech recognition. If the masker became speech-spectrum noise, significant release of target speech occurred only at a few short intermasker intervals less than 4 msec. Thus, the release of target speech from speech masking over a range of intermasker intervals between 4 and 32 msec cannot be explained by a reduction in energetic masking, and perceptual integration of the leading and lagging speech maskers must play a role in reducing informational masking of target speech. Although in the Rakerd et al. study the time-reversed speech was not used, on the basis of both the results of the present study and the results of the Freyman et al. (2001) study, it can be expected that if the masker becomes time-reversed speech under the experimental conditions used in the Rakerd et al. study, the maximum intermasker interval for significantly releasing target speech must be shorter than 32 msec because time-reversed speech has both smaller perceptual fusion tendency and smaller informational-masking effectiveness than normal-order speech.

This fusion-enhancing mechanism underlying the improvement of speech recognition in noisy, reverberant environments may reflect a more general cross-time perceptual “grouping” strategy of the brain for unmasking speech signals. As summarized by Moore (2003), temporal integration of acoustic signals over time, which improves detection and discrimination under masking conditions, does not involve a simple summation or accumulation process but is based on the formation of the internal representation of acoustic inputs. Because temporal integration is also based on temporal storage of acoustic details (Huang, Huang, et al., 2009; Huang, Wu, & Li, 2009; Li, Huang, Wu, Qi, & Schneider, 2009; Huang, Kong, Fan, Wu, & Li, 2008), the fusion-tendency enhancement specifically induced by the normal-order speech TAF may be due to an expansion of the temporal storage of the internal representation of speech signals when top-down modulations of the speech-processing cortical areas are elicited.

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